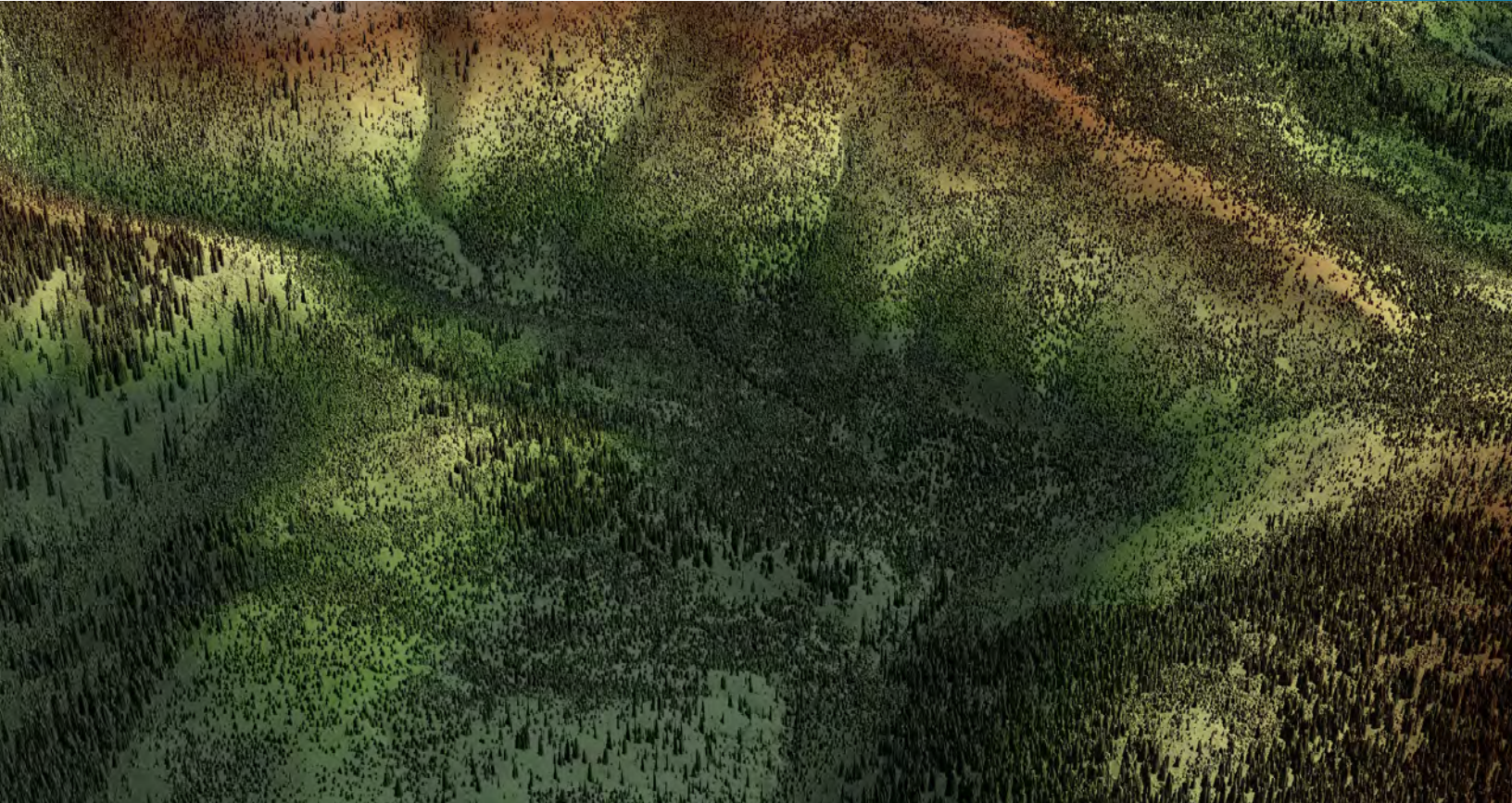


N|V|5

GEOSPATIAL

powered by QUANTUM SPATIAL



MT_RAVALLIGRANITECUSTERPOWDERRIVER_2019_B19 LIDAR PROCESSING REPORT

Work Package: 183671

Work Unit: 220298

2021

Submitted: August 20, 2021

Prepared for:



1400 Independence Road
Rolla, MO 65401

573.308.3500

Prepared by:

N|V|5

GEOSPATIAL

powered by QUANTUM SPATIAL

523 Wellington Way, Suite 375
Lexington, KY 40503

859.277.8700

Contents

1. Summary / Scope	1
1.1. Summary	1
1.2. Scope	1
1.3. Coverage	1
1.4. Duration	1
1.5. Issues	1
2. Planning / Equipment	4
2.1. Flight Planning	4
2.2. Lidar Sensor	4
2.3. Aircraft.....	7
2.4. Time Period	8
3. Processing Summary	10
3.1. Flight Logs.....	10
3.2. Lidar Processing.....	11
3.3. LAS Classification Scheme	12
3.4. Classified LAS Processing	12
3.5. Hydro-Flattened Breakline Processing	13
3.6. Hydro-Flattened Raster DEM Processing.....	13
3.7. Intensity Image Processing.....	14
3.8. First Return DSM Processing.....	14
3.9. Height Separation Raster Processing	14
4. Project Coverage Verification	16
5. Geometric Accuracy	18
5.1. Horizontal Accuracy	18
5.2. Relative Vertical Accuracy	19
6. Ground Control and Check Point Collection	20
6.1. Calibration Control Point Testing.....	20
6.2. Point Cloud Testing	20
6.3. Digital Elevation Model (DEM) Testing.....	20
Project Report Appendices	xxv
Appendix A	xxvi

List of Figures

Figure 1. Work Unit AOI.....3
 Figure 2. Planned Flight Lines5
 Figure 3. Riegl VQ1560i, and VQ1560ii Lidar Sensors6
 Figure 4. Some of NV5 Geospatial’s Planes7
 Figure 5. Lidar Tile Layout..... 15
 Figure 6. Lidar Coverage 17
 Figure 7. Calibration Control Point Locations..... 22
 Figure 8. QC Checkpoint Locations - NVA 23
 Figure 9. QC Checkpoint Locations - VVA 24

List of Tables

Table 1. Originally Planned Lidar Specifications1
 Table 2. Lidar System Specifications6
 Table 3. LAS Classifications..... 12

List of Appendices

Appendix A: Flight Logs

1. Summary / Scope

1.1. Summary

This report contains a summary of the MT_RavalliGraniteCusterPowderRiver_2019_B19, Work Unit 220298 lidar acquisition task order, issued by USGS under their Contract G16PC00016 on September 23, 2019. This delivery includes QL1 data and yielded a project area covering approximately 1,658 square miles over Montana. The intent of this document is only to provide specific validation information for the data acquisition/collection, processing, and production of deliverables completed as specified in the task order.

1.2. Scope

Aerial topographic lidar was acquired using state of the art technology along with the necessary surveyed ground control points (GCPs) and airborne GPS and inertial navigation systems. The aerial data collection was designed with the following specifications listed in Table 1 below.

Table 1. Originally Planned Lidar Specifications

Average Point Density	Flight Altitude (AGL)	Field of View	Minimum Side Overlap	RMSEz
8 pts / m ²	1824 m	58.5°	50%	≤ 10 cm

1.3. Coverage

The work unit boundary covers approximately 1,658 square miles over Montana. A buffer of 100 meters was created to meet task order specifications. Project extents are shown in Figure 1.

1.4. Duration

Lidar data was acquired from May 9, 2020 to August 29, 2020 in 42 total lifts. See “Section: 2.4. Time Period” for more details.

1.5. Issues

There were no major issues to report for this project.

MT_RavalliGraniteCusterPowderRiver_2019_B19 Work Unit 220298 Projected Coordinate System: State Plane Montana FIPS 2500 Horizontal Datum: NAD 1983 (2011) Vertical Datum: NAVD88 (GEOID 12b) Units: Meters	
Lidar Point Cloud	Classified Point Cloud in .LAS 1.4 format
Rasters	<ul style="list-style-type: none"> • 0.5-meter Hydro-flattened Bare Earth Digital Elevation Model (DEM) in GeoTIFF format • 0.5-meter First Return Digital Surface Model (DSM) in GeoTIFF format • 0.5-meter Intensity images in GeoTIFF format • 0.5-meter Swath Separation images in GeoTIFF format
Vectors	Shapefiles (*.shp) <ul style="list-style-type: none"> • Project Boundary • Lidar Tile Index Geodatabase (*.gdb) <ul style="list-style-type: none"> • Continuous Hydro-flattened Breaklines
Reports	Reports in PDF format <ul style="list-style-type: none"> • Focus on Delivery • Focus on Accuracy • Processing Report
Metadata	XML Files (*.xml) <ul style="list-style-type: none"> • Breaklines • Classified Point Cloud • DEM • Intensity Imagery • DSM

MT_RavalliGraniteCusterPowderRiver_2019_B19

Work Unit 220298 Boundary

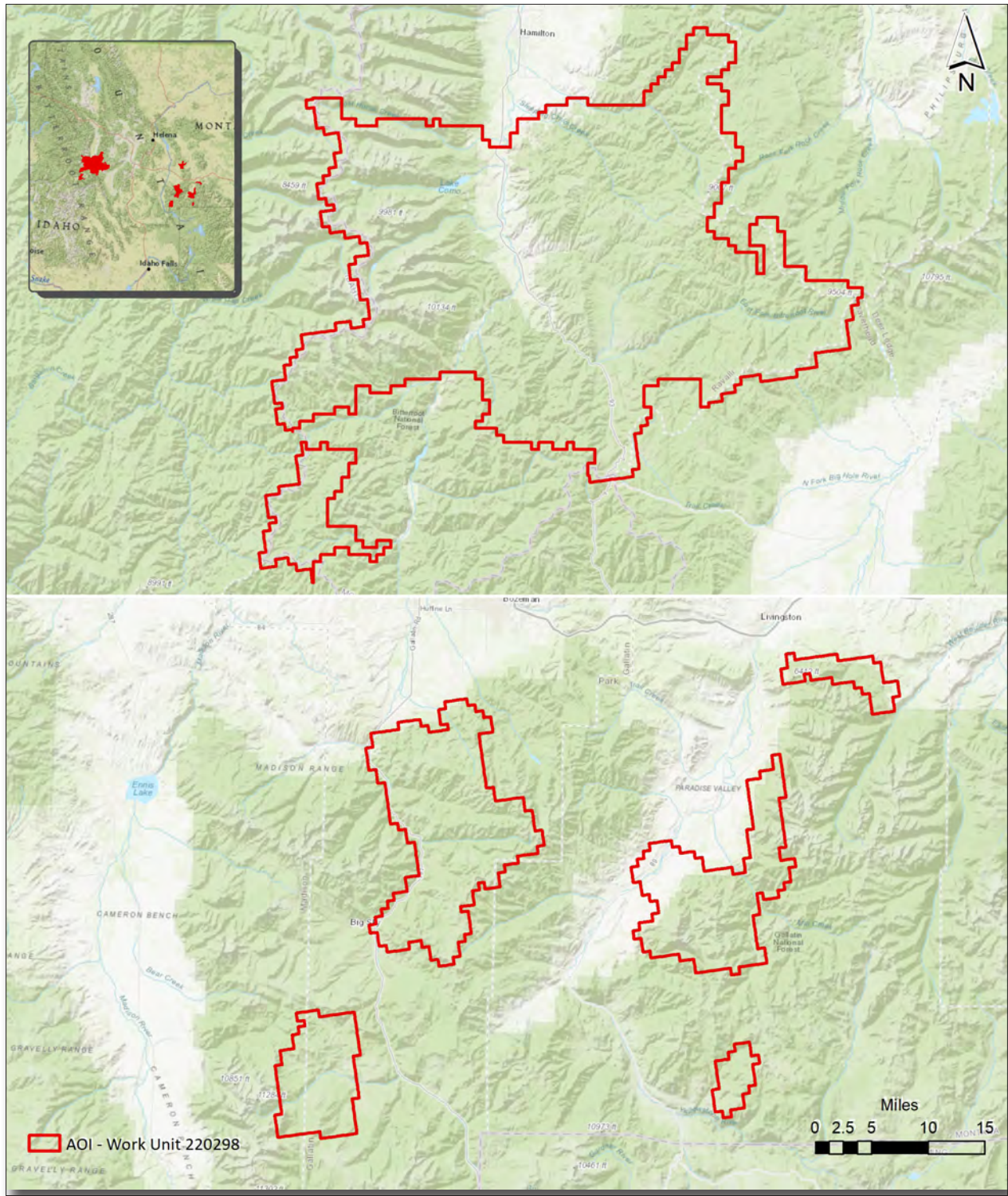


Figure 1. Work Unit AOI

2. Planning / Equipment

2.1. Flight Planning

Flight planning was based on the unique project requirements and characteristics of the project site. The basis of planning included: required accuracies, type of development, amount / type of vegetation within project area, required data posting, and potential altitude restrictions for flights in project vicinity.

Detailed project flight planning calculations were performed for the project using RiPARAMETER planning software. Planned flight lines are shown in Figure 2.

2.2. Lidar Sensor

NV5 Geospatial utilized the following sensors for lidar data collection:

Riegl VQ1560i: 3061, 3546
Riegl VQ1560ii: 4040, 4045

The Riegl 1560i system has a laser pulse repetition rate of up to 2 MHz resulting in more than 1.3 million measurements per second. The system utilizes a Multi-Pulse in the Air option (MPIA). The sensor is also equipped with the ability to measure up to an unlimited number of targets per pulse from the laser.

The Riegl 1560II system is a dual channel waveform processing airborne scanning system. It has a laser pulse repetition rate of up to 4 MHz resulting in up to 2.66 million measurements per second. The system utilizes a Multi-Pulse in the Air option (MPIA) and an integrated IMU/GNSS unit.

A brief summary of the aerial acquisition parameters for the project are shown in the Lidar System Specifications in Table 2.

MT_RavalliGraniteCusterPowderRiver_2019_B19

Work Unit 220298 Planned Flight Lines

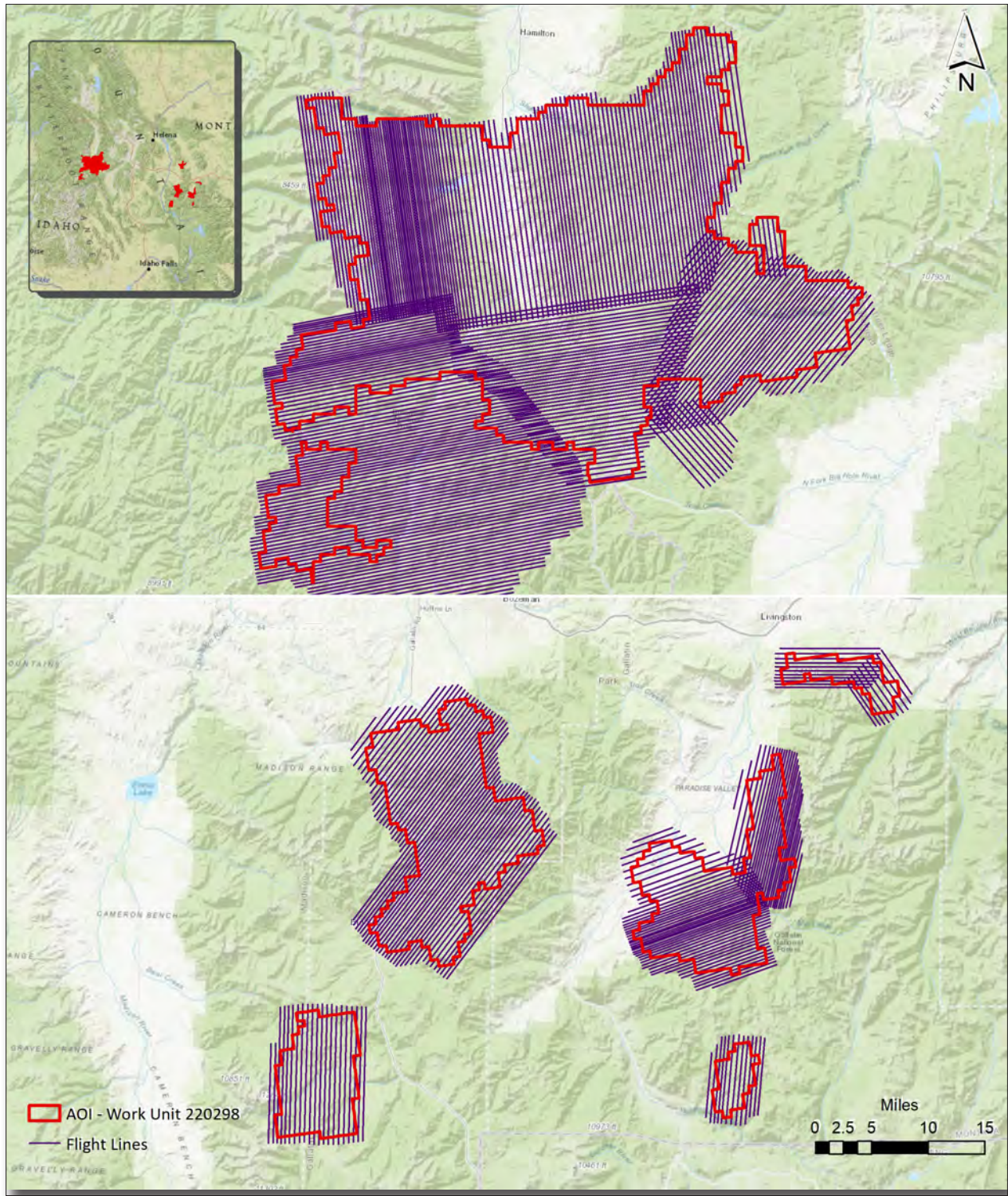


Figure 2. Planned Flight Lines

Table 2. Lidar System Specifications

		Riegl VQ1560i (3061, 3546, 4045; QL1)	Riegl VQ1560ii (3061, 3546, 4040; QL1)
Terrain and Aircraft Scanner	Flying Height	2079 m	1824 m
	Recommended Ground Speed	115 kts	145 kts
Scanner	Field of View	58.5°	58.5°
	Scan Rate Setting Used	2 x 80.6 Hz	2 x 117 Hz
Laser	Laser Pulse Rate Used	2 x 500 kHz	2 x 700 kHz
	Multi Pulse in Air Mode	yes	yes
Coverage	Full Swath Width	2330 m	2044 m
	Line Spacing	1048 m	920 m
Point Spacing and Density	Average Point Spacing	<0.35 m	<0.35 m
	Average Point Density	9.68 pts / m ²	12.22 pts / m ²

Figure 3. Riegl VQ1560i, and VQ1560ii Lidar Sensors



2.3. Aircraft

All flights for the project were accomplished through the use of customized planes. Plane type and tail numbers are listed below.

LiDAR Collection Planes

- Piper Navajo, Tail Numbers: N22GE
- Cessna Caravan (single-turboprop), Tail Numbers: N704MD, N604MD, N208JA, N840JA

These aircraft provided an ideal, stable aerial base for LiDAR acquisition. These aerial platforms have relatively fast cruise speeds, which are beneficial for project mobilization / demobilization while maintaining relatively slow stall speeds, proving ideal for collection of high-density, consistent data posting using a state-of-the-art Riegl Lidar systems, Some of NV5 Geospatial's operating aircraft can be seen in Figure 4 below.

Figure 4. Some of NV5 Geospatial's Planes



2.4. Time Period

Project specific flights were conducted between May 9, 2020 and August 29, 2020. Forty-two aircraft lifts were completed. Accomplished lifts are listed below.

Lift	Start UTC	End UTC
05092020A (SN3546,N704MD)	5/09/2020 5:24:31 PM	5/09/2020 7:29:13 PM
06022020A (SN4045,N208JA)	6/02/2020 3:52:34 PM	6/02/2020 8:36:20 PM
06242020A (SN3061,N840JA)	6/24/2020 5:10:30 PM	6/24/2020 5:10:32 PM
06262020A (SN3061,N840JA)	6/26/2020 4:34:16 PM	6/26/2020 8:11:26 PM
07222020B (SN4040,N22GE)	7/22/2020 7:31:03 PM	7/22/2020 8:27:47 PM
07232020A (SN4040,N22GE)	7/23/2020 3:12:18 PM	7/23/2020 3:24:40 PM
07252020A (SN3546,N704MD)	7/25/2020 9:58:43 PM	7/25/2020 11:15:13 PM
07252020A (SN4040,N22GE)	7/25/2020 2:52:42 PM	7/25/2020 6:07:51 PM
07252020B (SN4040,N22GE)	7/25/2020 8:04:05 PM	7/25/2020 10:17:24 PM
07262020A (SN4040,N22GE)	7/26/2020 2:56:11 PM	7/26/2020 6:57:09 PM
07262020A1 (SN3546,N704MD)	7/26/2020 3:27:17 PM	7/26/2020 5:59:02 PM
07262020A2 (SN3546,N704MD)	7/26/2020 6:12:55 PM	7/26/2020 8:15:45 PM
07272020A (SN3546,N704MD)	7/27/2020 3:45:55 PM	7/27/2020 9:35:42 PM
07272020B (SN4040,N22GE)	7/27/2020 4:46:54 PM	7/27/2020 6:33:40 PM
07282020A (SN3546,N704MD)	7/28/2020 3:25:50 PM	7/28/2020 8:22:49 PM
07282020B (SN4040,N22GE)	7/28/2020 4:12:03 PM	7/28/2020 6:02:26 PM
07292020A (SN3546,N704MD)	7/29/2020 3:09:01 PM	7/29/2020 7:41:34 PM
07292020A (SN4040,N22GE)	7/29/2020 3:48:51 PM	7/29/2020 6:05:20 PM
07292020B (SN4040,N22GE)	7/29/2020 7:31:25 PM	7/29/2020 8:44:20 PM
07302020A (SN3546,N704MD)	7/30/2020 2:14:23 PM	7/30/2020 8:25:15 PM
07312020A (SN3546,N704MD)	7/31/2020 1:55:25 PM	7/31/2020 8:40:59 PM
08012020A (SN3546,N704MD)	8/01/2020 2:27:33 PM	8/01/2020 8:25:17 PM
08042020A (SN3546,N704MD)	8/04/2020 5:56:17 PM	8/04/2020 8:22:53 PM
08052020A (SN3546,N704MD)	8/05/2020 2:08:14 PM	8/05/2020 8:07:50 PM
08072020A (SN3546,N704MD)	8/07/2020 4:06:08 PM	8/07/2020 5:35:49 PM

Lift	Start UTC	End UTC
08082020A (SN3546,N704MD)	8/08/2020 1:56:15 PM	8/08/2020 5:56:12 PM
08082020B (SN3546,N704MD)	8/08/2020 8:04:14 PM	8/08/2020 10:22:18 PM
08092020A (SN3546,N704MD)	8/09/2020 1:51:44 PM	8/09/2020 6:06:24 PM
08092020A (SN4040,N22GE)	8/09/2020 1:46:16 PM	8/09/2020 3:29:38 PM
08102020A (SN4040,N22GE)	8/10/2020 4:19:21 PM	8/10/2020 4:49:21 PM
08172020A (SN4040,N22GE)	8/17/2020 3:52:21 PM	8/17/2020 5:34:33 PM
08172020B (SN4040,N22GE)	8/17/2020 7:02:01 PM	8/17/2020 7:37:41 PM
08182020A (SN4040,N22GE)	8/18/2020 2:33:55 PM	8/18/2020 5:31:40 PM
08212020A (SN3546,N704MD)	8/21/2020 3:20:33 PM	8/21/2020 5:30:04 PM
08222020B (SN3546,N704MD)	8/22/2020 2:27:54 PM	8/22/2020 3:04:43 PM
08222020C (SN3546,N704MD)	8/22/2020 3:48:45 PM	8/22/2020 6:10:40 PM
08232020A (SN3546,N704MD)	8/23/2020 2:21:46 PM	8/23/2020 6:12:29 PM
08262020A (SN4040,N22GE)	8/26/2020 3:57:29 PM	8/26/2020 4:48:09 PM
08262020A (SN4046,N604MD)	8/26/2020 4:01:33 PM	8/26/2020 7:15:52 PM
08282020A (SN4040,N22GE)	8/28/2020 3:58:16 PM	8/28/2020 5:45:05 PM
08282020B (SN4046,N604MD)	8/28/2020 4:14:02 PM	8/28/2020 4:57:40 PM
08292020A (SN4040,N22GE)	8/29/2020 2:51:04 PM	8/29/2020 5:54:10 PM

3. Processing Summary

3.1. Flight Logs

Flight logs were completed by lidar sensor technicians for each mission during acquisition. These logs depict a variety of information, including:

- Job / Project #
- Flight Date / Lift Number
- FOV (Field of View)
- Scan Rate (HZ)
- Pulse Rate Frequency (Hz)
- Ground Speed
- Altitude
- Base Station
- PDOP avoidance times
- Flight Line #
- Flight Line Start and Stop Times
- Flight Line Altitude (AMSL)
- Heading
- Speed
- Returns
- Crab

Notes: (Visibility, winds, ride, weather, temperature, dew point, pressure, etc).

3.2. Lidar Processing

Applanix + POSPac software was used for post-processing of airborne GPS and inertial data (IMU), which is critical to the positioning and orientation of the lidar sensor during all flights. Applanix POSPac combines aircraft raw trajectory data with stationary GPS base station data yielding a “Smoothed Best Estimate Trajectory” (SBET) necessary for additional post processing software to develop the resulting geo-referenced point cloud from the lidar missions.

During the sensor trajectory processing (combining GPS & IMU datasets) certain statistical graphs and tables are generated within the Applanix POSPac processing environment which are commonly used as indicators of processing stability and accuracy. This data for analysis include: max horizontal / vertical GPS variance, separation plot, altitude plot, PDOP plot, base station baseline length, processing mode, number of satellite vehicles, and mission trajectory.

Point clouds were created using RiPROCESS software. The generated point cloud is the mathematical three dimensional composite of all returns from all laser pulses as determined from the aerial mission. The point cloud is imported into GeoCue distributive processing software. Imported data is tiled and then calibrated using TerraMatch and proprietary software. Using TerraScan, the vertical accuracy of the surveyed ground control is tested and any bias is removed from the data. TerraScan and TerraModeler software packages are then used for automated data classification and manual cleanup. The data are manually reviewed and any remaining artifacts removed using functionality provided by TerraScan and TerraModeler.

DEMs and Intensity Images are then generated using proprietary software. In the bare earth surface model, above-ground features are excluded from the data set. Global Mapper is used as a final check of the bare earth dataset.

Finally, proprietary software is used to perform statistical analysis of the LAS files.

Software	Version
RiPROCESS	1.8.6
Applanix + POSPac	8.6
GeoCue	2020.1.22.1
Global Mapper	19.1;20.1
TerraModeler	21.008
TerraScan	21.016
TerraMatch	21.007

3.3. LAS Classification Scheme

The classification classes are determined by the USGS Version 1.3 specifications and are an industry standard for the classification of lidar point clouds. All data starts the process as Class 1 (Unclassified), and then through automated classification routines, the classifications are determined using TerraScan macro processing.

The classes used in the dataset are as follows and have the following descriptions:

Table 3. LAS Classifications

	Classification Name	Description
1	Processed, but Unclassified	Laser returns that are not included in the ground class, or any other project classification
2	Bare earth	Laser returns that are determined to be ground using automated and manual cleaning algorithms
6	Buildings	Points falling on buildings, structures inside of water bodies, docks, and piers.
7	Low Noise	Laser returns that are often associated with scattering from reflective surfaces, or artificial points below the ground surface
9	Water	Laser returns that are found inside of hydro features
17	Bridge Deck	Laser returns falling on bridge decks
18	High Noise	Laser returns that are often associated with birds or artificial points above the ground surface
20	Ignored Ground	Ground points that fall within the given threshold of a collected hydro feature.
21	Snow	Ground points that fall on snow, where identifiable

3.4. Classified LAS Processing

The bare earth surface is then manually reviewed to ensure correct classification on the Class 2 (Ground) points. After the bare- earth surface is finalized; it is then used to generate all hydro-breaklines through heads-up digitization.

All ground (ASPRS Class 2) Lidar data inside of the Lake Pond and Double Line Drain hydro flattening breaklines were then classified to water (ASPRS Class 9) using TerraScan macro functionality. A buffer of 3 feet was also used around each hydro flattened feature to classify these ground (ASPRS Class 2) points to Ignored ground (ASPRS Class 20). All Lake Pond Island and Double Line Drain Island features were checked to ensure that the ground (ASPRS Class 2) points were reclassified to the correct classification after the automated classification was

completed.

Any noise that was identified either through manual review or automated routines was classified to the appropriate class (ASPRS Class 7 and/or ASPRS Class 18) followed by flagging with the withheld bit.

All data was manually reviewed and any remaining artifacts removed using functionality provided by TerraScan and TerraModeler. Global Mapper is used as a final check of the bare earth dataset. GeoCue was then used to create the deliverable industry-standard LAS files for all point cloud data. NV5 Geospatial's proprietary software was used to perform final statistical analysis of the classes in the LAS files, on a per tile level to verify final classification metrics and full LAS header information.

3.5. Hydro-Flattened Breakline Processing

Class 2 (ground) lidar points was used to create a bare earth surface model. The surface model was then used to heads-up digitize 2D breaklines of inland streams and rivers with a 100-foot nominal width and inland ponds and lakes of 2 acres or greater surface area.

Elevation values were assigned to all inland streams and rivers using NV5 Geospatial's proprietary software.

All Ground (ASPRS Class 2) lidar data inside of the collected inland breaklines were then classified to Water (ASPRS Class 9) using TerraScan macro functionality. A buffer of 1.5 feet was also used around each hydro-flattened feature. These points were moved from ground (ASPRS Class 2) to Ignored Ground (ASPRS Class 20).

The breakline files were then translated to Esri file geodatabase format using Esri conversion tools.

Breaklines are reviewed against lidar intensity imagery to verify completeness of capture. All breaklines are then compared to TINs (triangular irregular networks) created from ground only points prior to water classification. The horizontal placement of breaklines is compared to terrain features and the breakline elevations are compared to lidar elevations to ensure all breaklines match the lidar within acceptable tolerances. Some deviation is expected between breakline and lidar elevations due to monotonicity, connectivity, and flattening rules that are enforced on the breaklines. Once completeness, horizontal placement, and vertical variance is reviewed, all breaklines are reviewed for topological consistency and data integrity using a combination of Esri Data Reviewer tools and proprietary tools.

3.6. Hydro-Flattened Raster DEM Processing

Class 2 Lidar in conjunction with the hydro breaklines were used to create 0.5-meter, hydro-flattened raster DEMs. Using automated scripting routines within proprietary software, a GeoTIFF file was created for each tile. Each surface is reviewed using Global Mapper to check for any surface anomalies or incorrect elevations found within the surface.

3.7. Intensity Image Processing

GeoCue software was used to create the deliverable intensity images. All withheld points were ignored during this process. This helps to ensure a more aesthetically pleasing image. The GeoCue software was then used to verify full project coverage as well. GeoTIFF files with a cell size of 0.5-meter were then provided as the deliverable for this dataset requirement.

3.8. First Return DSM Processing

First return lidar points were used to create a 0.5-meter first-return raster DSM. Using automated scripting routines within proprietary software, GeoTIFF files were created for each tile. Each surface is reviewed using Global Mapper to check for any surface anomalies or incorrect elevations found within the surface.

3.9. Height Separation Raster Processing

Swath Separation Images are rasters that represent the interswath alignment between flight lines and provide a qualitative evaluation of the positional quality of the point cloud. Proprietary software was used to create 1-meter raster images in GeoTIFF format.

MT_RavalliGraniteCusterPowderRiver_2019_B19

Work Unit 220298 Tile Layout

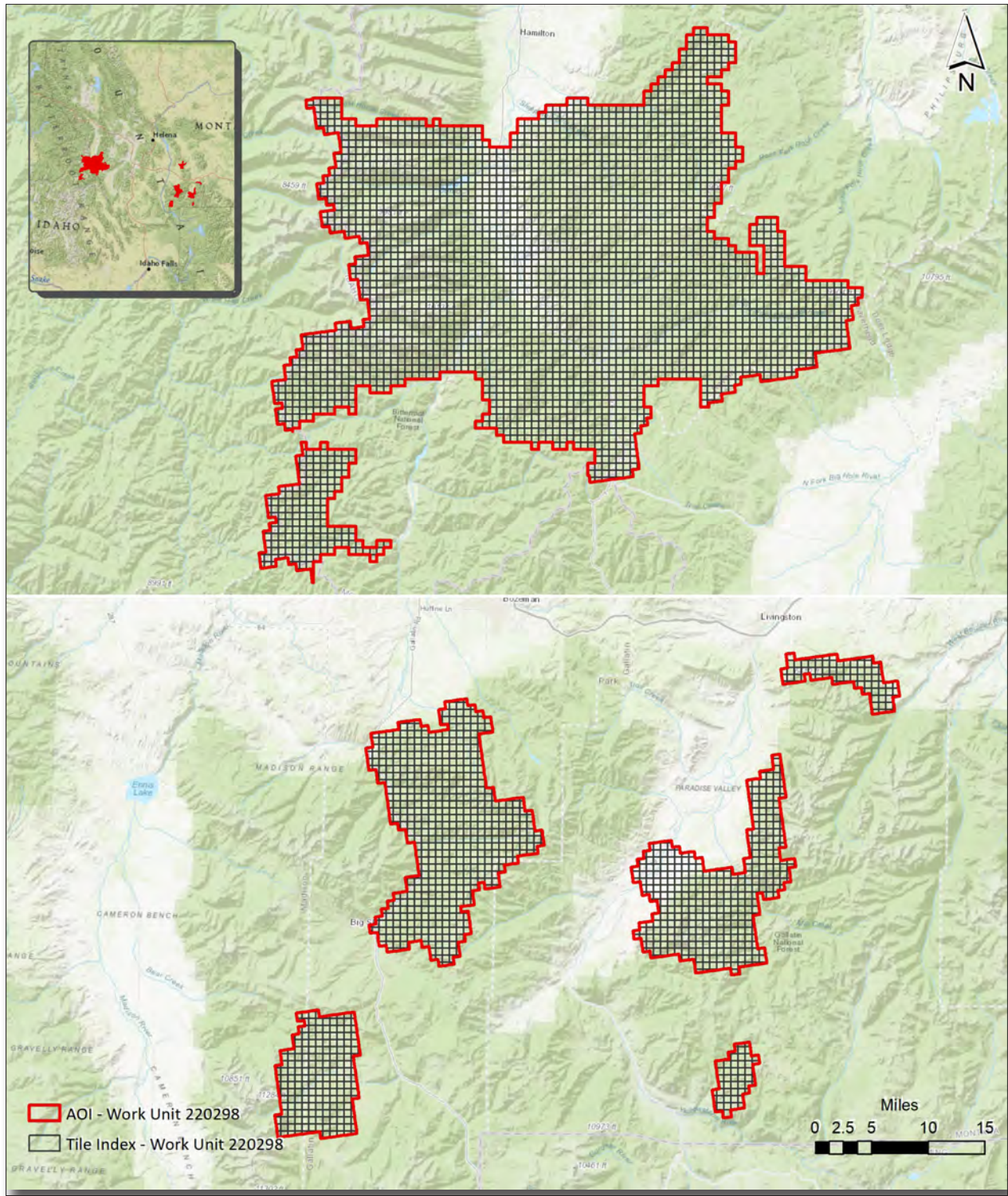


Figure 5. Lidar Tile Layout

4. Project Coverage Verification

Coverage verification was performed by comparing coverage of processed .LAS files captured during project collection to generate project shape files depicting boundaries of specified project areas. Please refer to Figures 6.

MT_RavalliGraniteCusterPowderRiver_2019_B19

Work Unit 220298 Coverage

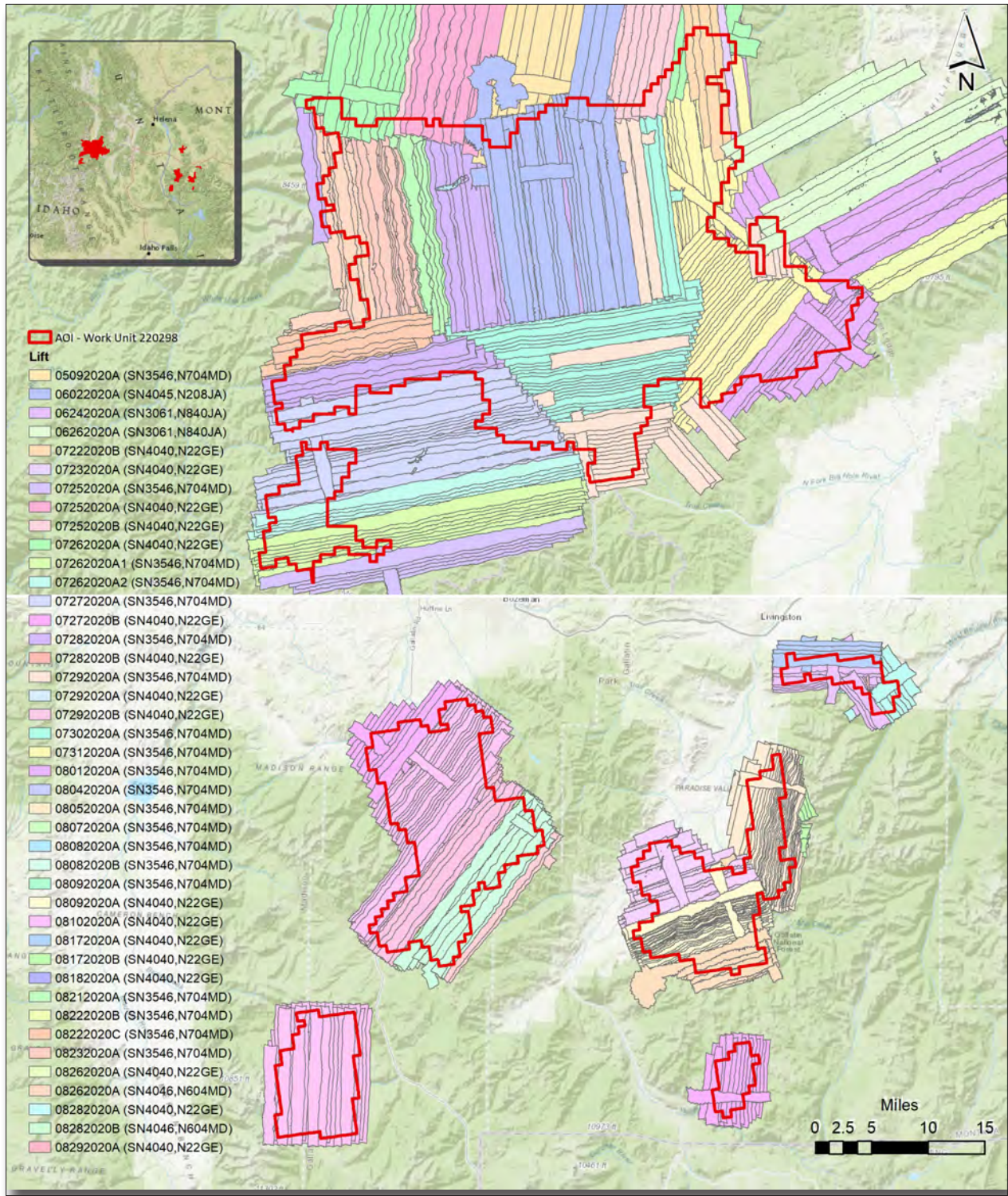


Figure 6. Lidar Coverage

5. Geometric Accuracy

5.1. Horizontal Accuracy

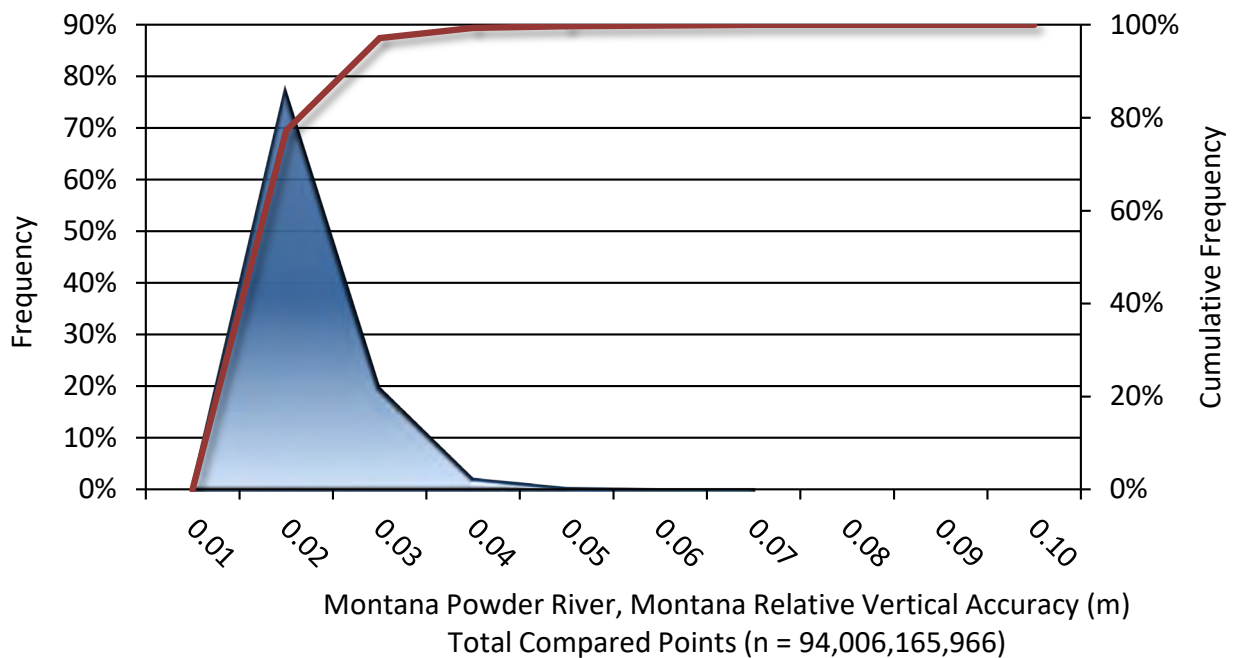
Lidar horizontal accuracy is a function of Global Navigation Satellite System (GNSS) derived positional error, flying altitude, and INS derived attitude error. The obtained $RMSE_r$ value is multiplied by a conversion factor of 1.7308 to yield the horizontal component of the National Standards for Spatial Data Accuracy (NSSDA) reporting standard where a theoretical point will fall within the obtained radius 95% of the time. Based on a flying altitude of 2300 meters, an IMU error of 0.002 decimal degrees, and a GNSS positional error of 0.018 meters, this project was compiled to meet 0.40 meter horizontal accuracy at the 95% confidence level. A summary is shown below.

Horizontal Accuracy	
$RMSE_r$	0.23 m
	0.76 ft
ACC_r	0.40 m
	1.31 ft

5.2. Relative Vertical Accuracy

Relative vertical accuracy refers to the internal consistency of the data set as a whole: the ability to place an object in the same location given multiple flight lines, GPS conditions, and aircraft attitudes. When the lidar system is well calibrated, the swath-to-swath vertical divergence is low (<0.10 meters). The relative vertical accuracy was computed by comparing the ground surface model of each individual flight line with its neighbors in overlapping regions. The average (mean) line to line relative vertical accuracy for Work Unit 220298 was 0.058 feet (0.018 meters). A summary is shown below.

Relative Vertical Accuracy	
Sample	730 flight line surfaces
Average	0.058 ft
	0.018 m
Median	0.057 ft
	0.017 m
RMSE	0.063 ft
	0.019 m
Standard Deviation (1σ)	0.016 ft
	0.005 m
1.96σ	0.031 ft
	0.010 m



6. Ground Control and Check Point Collection

NV5 Geospatial utilized 217 ground control (calibration) points along with 353 blind QA points (208 NVA points and 145 VVA points) in Non-Vegetated and Vegetated land cover classifications. QA points were used as an independent test of the accuracy of this project.

The required accuracy testing was performed on the lidar dataset (both the lidar point cloud and derived DEM's) according to the USGS Lidar Base Specification Version 1.3.

6.1. Calibration Control Point Testing

Figure 7 shows the location of each bare earth calibration point for the project area. TerraScan was used to perform a quality assurance check using the lidar bare earth calibration points. The results of the surface calibration are not an independent assessment of the accuracy of these project deliverables, but the statistical results do provide additional feedback as to the overall quality of the elevation surface.

6.2. Point Cloud Testing

The project specifications require that only Non-Vegetated Vertical Accuracy (NVA) be computed for the raw lidar point cloud. The required accuracy (ACCz) is: 19.6 cm at a 95% confidence level, derived according to NSSDA, i.e., based on RMSE of 10 cm in the “bare earth” and “urban” land cover classes. The NVA was tested with 208 checkpoints located in bare earth and urban (non-vegetated) areas. These check points were not used in the calibration or post processing of the lidar point cloud data. The checkpoints were distributed throughout the project area and were surveyed using GPS techniques. See survey report for additional survey methodologies.

Elevations from the unclassified lidar surface were measured for the x,y location of each check point. Elevations interpolated from the lidar surface were then compared to the elevation values of the surveyed control points. AccuracyZ has been tested to meet 19.6 cm or better Non-Vegetated Vertical Accuracy at 95% confidence level using $RMSE(z) \times 1.9600$ as defined by the National Standards for Spatial Data Accuracy (NSSDA); assessed and reported using National Digital Elevation Program (NDEP)/ASPRS Guidelines.

6.3. Digital Elevation Model (DEM) Testing

The project specifications require the accuracy (ACCz) of the derived DEM be calculated and reported in two ways:

1. The required NVA is: 19.6 cm at a 95% confidence level, derived according to NSSDA, i.e., based on RMSE of 10 cm in the “bare earth” and “urban” land cover classes. This is a required accuracy. The NVA was tested with 208 checkpoints located in bare earth and urban (non-vegetated) areas. See Figure 8.

2. **Vegetated Vertical Accuracy (VVA):** VVA shall be reported for “brushlands/low trees” and “tall weeds/crops” land cover classes. The target VVA is: 29.4 cm at the 95th percentile, derived according to ASPRS Guidelines, Vertical Accuracy Reporting for Lidar Data, i.e., based on the 95th percentile error in all vegetated land cover classes combined. This is a target accuracy. The VVA was tested with 145 checkpoints located in tall weeds/crops and brushlands/low trees (vegetated) areas. The checkpoints were distributed throughout the project area and were surveyed using GPS techniques. See Figure 9.

AccuracyZ has been tested to meet 19.6 cm or better Non-Vegetated Vertical Accuracy at 95% confidence level using $RMSE(z) \times 1.9600$ as defined by the National Standards for Spatial Data Accuracy (NSSDA); assessed and reported using National Digital Elevation Program (NDEP)/ASRPS Guidelines.

A brief summary of results are listed below.

	Target	Measured	Point Count
Raw NVA	0.196 m	.0692 m	208
NVA	0.196 m	.0656 m	208
VVA	0.294 m	.2116 m	145

MT_RavalliCusterGranitePowderRiver Calibration Points

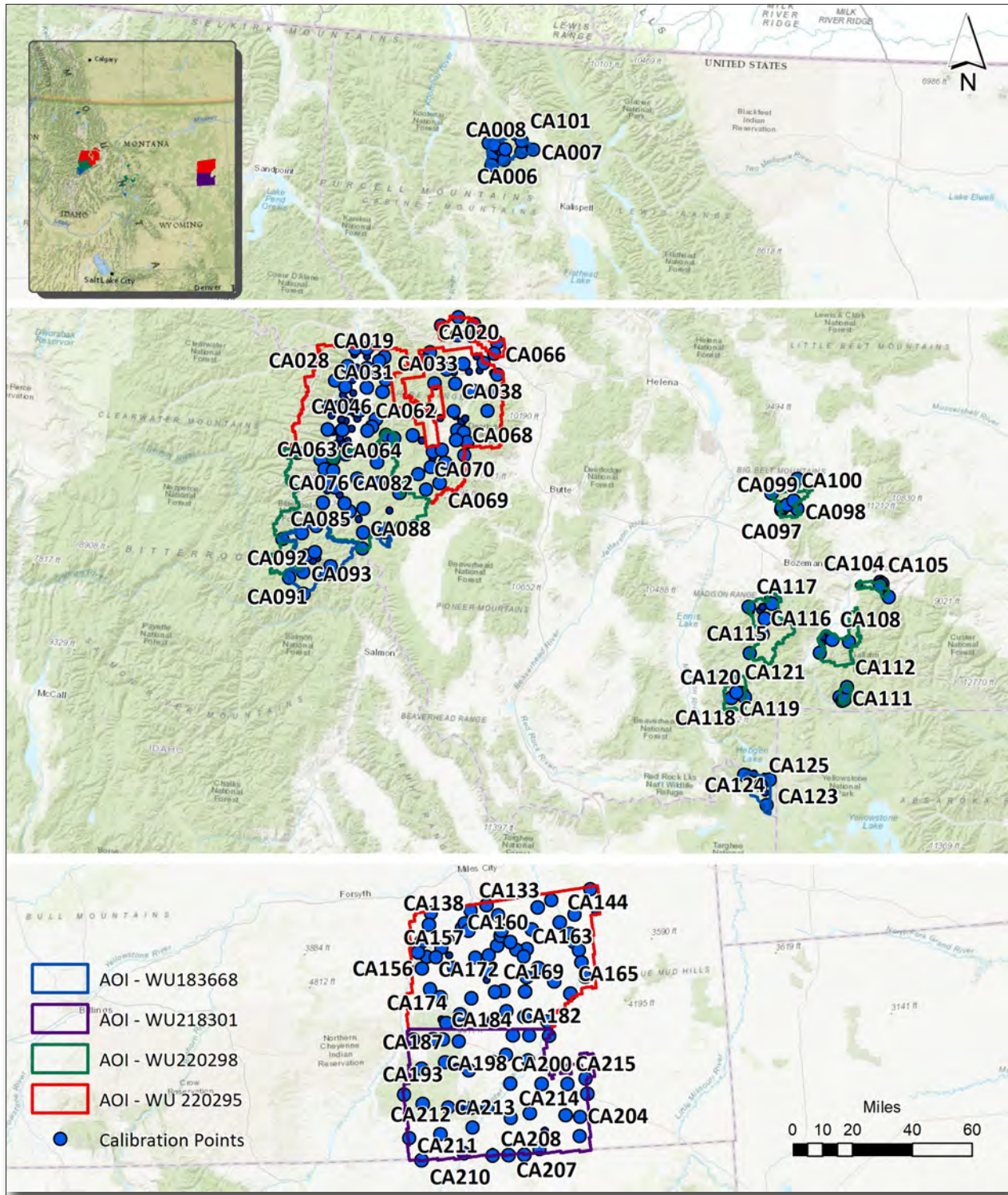


Figure 7. Calibration Control Point Locations

MT_RavalliCusterGranitePowderRiver NVA Points

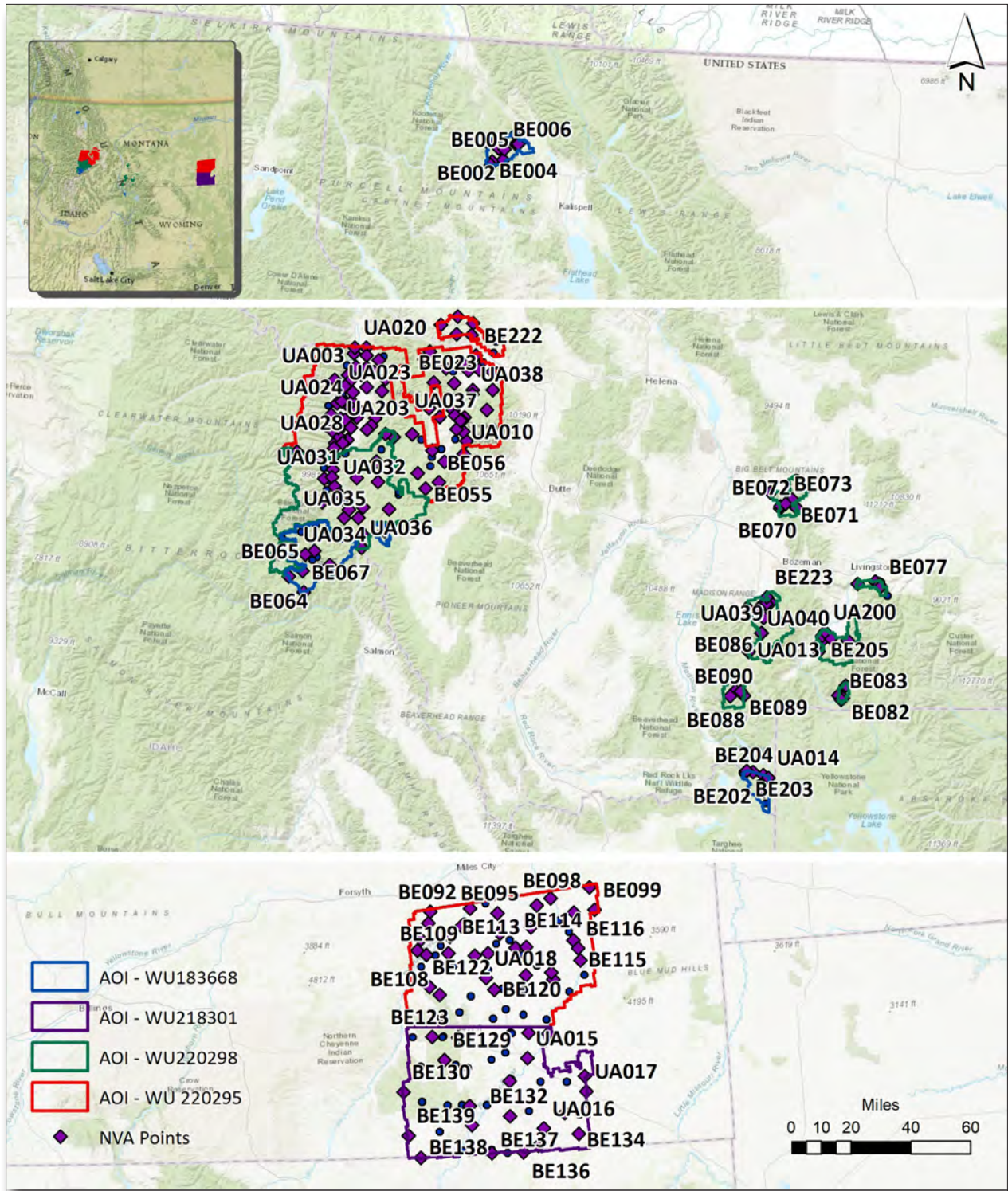


Figure 8. QC Checkpoint Locations - NVA

MT_RavalliCusterGranitePowderRiver VVA Points

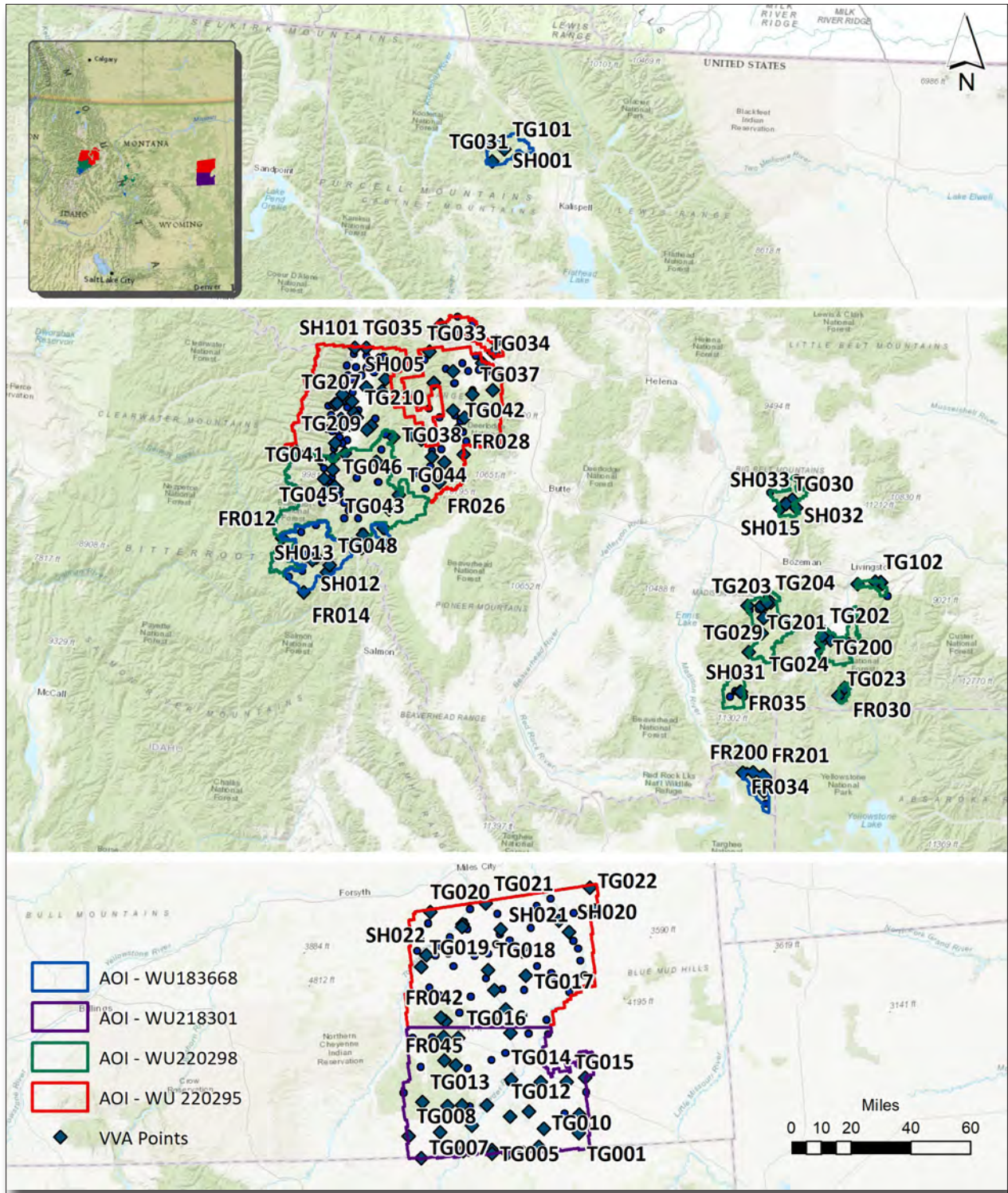


Figure 9. QC Checkpoint Locations - VVA

Project Report Appendices

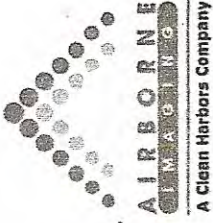
The following section contains the appendices as listed in
the **MT_RavalliGraniteCusterPowderRiver**
Lidar Project Report.

Appendix A

Flight Logs

Julian Day 292 Flight A

LIDAR Flight Log



Date OCT 19, 2019 Aircraft C-FFRY
 Project 3186 OSI Powder Riv. Pilot MACQUARRIE
 Location SHERIDAN, WYO Operator WESTERGARD
 Mission Objective _____

System RIEGL 1560i
 Unit 43
 IMU _____
 GPS Rx Trimble
 Scanner 1 Drive _____
 Scanner 2 Drive _____

Additional Notes _____
 Time to next maintenance: 50 hr 100 hr

Aircraft Block Time	
Engine On 1705	Takeoff 1721
Engine Off 2105	Landing 2052
Total 4.0 hrs	Total 35 hrs

Mission Plan			
AGL Height	2000 m	Pulse Rate	500 kHz
Target Speed	160 kts	Scan Rate	169
Laser Current	100 %	FOV	60 degs

Static Alignment	GPS Time	
	Start	End
	Pre Mission 1712	1717
Post Mission 2058	2103	

Flight Line	LIDAR File Name	Flight Direction	GPS Time		Line Aborted	Mission ID	Comments
			Start	End			
Figure 8		∞	1753	1758			
X-LINE	431929201	355	1759	1803		175902	inertial
1001	431929202	85	1807	1813		180745	lots of turbulence.
1002	431929203	265	1815	1826		181552	
1003	431929204	85	1830	1840		183029	
1004	431929205	265	1843	1855		184349	
1005	431929206	85	1859	1910		185905	
1006	431929207	265	1913	1925		191340	
1007	431929208	85	1927	1939		192755	
1008	431929209	265	1941	1953		194137	
1009	431929210	85	1956	2007		195621	
Figure 8		∞	2007	2012			inertial



AIRBORNE
A Clean Harbors Company

LIDAR Flight Log

Julian Day 297 Flight A

Date	OCT 24, 2019	Aircraft	CFPRV
Project	3186-QSI-POWDER	Pilot	MACQUARRIE
Location	SHERIDAN, WY	Operator	WESTERGARD
Mission Objective			

System	REIGL 1560i
Unit	43
IMU	
GPS Rx	Trimble
Scanner 1 Drive	
Scanner 2 Drive	

Additional Notes

Time to next maintenance: 50 hr 100 hr

Aircraft Block Time	
Engine On	15:25
Takeoff	17:28
Engine Off	23:10
Landing	23:00
Total	5.9 hrs

Mission Plan			
AGL Height	2000 m	Pulse Rate	500 kHz
Target Speed	160 kts	Scan Rate	109
Laser Current	160 %	FOV	60°

Static Alignment	GPS Time	
	Start	End
Pre Mission	1719	1724
Post Mission	2304	2309

Flight Line	LIDAR File Name	Flight Direction	GPS Time		Line Aborted	Mission ID	Comments
			Start	End			
test		∞	1747	1749		179725	
Figure 8		∞	1804	1808			inertial
x line	431929701	355	1810	1816		181050	
2001	431929702	85	1821	1827		182142	
2002	431929704	265	1829	1839		182956	
2003	431929705	85	1845	1856		184512	
2004	431929706	265	1859	1911		185936	
2005	431929707	85	1914	1925		191438	
2006	431929708	265	1928	1939		192835	
2007	431929709	85	1943	1954		194310	
2008	431929710	265	1956	2008		195656	
2009	431929711	85	2011	2022		201112	
2010	431929112	265	2024	2036		202456	
2011	431929713	85	2038	2049		203856	
2012	431929714	265	2053	2103		205307	

LIDAR Flight Log

Julian Day 297 Flight A



Date	Oct 24, 2019	Aircraft	CFFRY
Project	3186 OSI Powder	Pilot	MACQUARRIE
Location	SHERIDAN WYO.	Operator	WESTERGARD
Mission Objective			

System	REIGL Q15601
Unit	1143
IMU	
GPS Rx	Trimble
Scanner 1 Drive	
Scanner 2 Drive	

Additional Notes

Time to next maintenance: 50 hr 100 hr

Aircraft Block Time			
Engine On	1715	Takeoff	1728
Engine Off	2310	Landing	2300
Total	5.9 hrs	Total	5.5 hrs

Mission Plan				
AGL Height	2000 m	Pulse Rate	500 kHz	
Target Speed	160 kts	Scan Rate	109	deg/s
Laser Current	100 %	FOV	60	

Static Alignment	GPS Time	
	Start	End
	Pre Mission	1719
Post Mission	2304	2309

Flight Line	LIDAR File Name	Flight Direction	GPS Time		Line Aborted		Mission ID	Comments
			Start	End	Time	nmi to End		
X-LINE	431929715	85	2110	2114			211019	
3069	431929716	175	2119	2127			211925	
3068	431929717	355	2130	2138			213011	
3067	431929715	175	2141	2150			214112	
3066	431929716	355	2153	2201			215303	
3065	431929718	175	2204	2211			220407	
Figure 8		∞	2211	2216				Inertial



AIRBORNE
IMAGING
A Clean Harbors Company

LIDAR Flight Log

Julian Day 298 Flight A

Date	Oct 25, 2016	Aircraft	C-FFRY
Project	2186 Qs1. POWDER	Pilot	MAOSVARRIE
Location	SHERIDAN, WYO	Operator	WESTERGARD
Mission Objective			

System	REIKL Q1560i
Unit	43
IMU	
GPS Rx	Trimble
Scanner 1 Drive	
Scanner 2 Drive	

Additional Notes	
Time to next maintenance:	<input type="checkbox"/> 50 hr <input type="checkbox"/> 100 hr

Aircraft Block Time			
Engine On	1538	Takeoff	1555
Engine Off	2153	Landing	2141
Total	6.3 hrs	Total	5.8 hrs

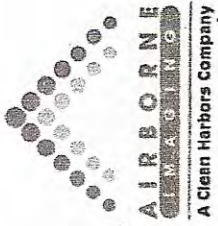
Mission Plan			
AGL Height	2000 m	Pulse Rate	500 kHz
Target Speed	100 kts	Scan Rate	109
Laser Current	100 %	FOV	60 degs

Static Alignment		GPS Time	
Pre Mission	1546	Start	End
Post Mission	2146	1546	1551
		2146	2151

Flight Line	LIDAR File Name	Flight Direction	GPS Time		Line Aborted		Mission ID	Comments
			Start	End	Time	nmi to End		
test		∞	1619	1621			161930	test
figure 8		∞	1624	1629				inertial
X-LINE	431929801	85	1629	1639			162953	
3064	431929802	355	1644	1653			164446	
3063	431929803	175	1656	1705			165619	
3062	431929804	355	1707	1716			170757	
3061	431929805	175	1719	1729			171946	
3060	431929806	355	1732	1741			173211	
3059	431929807	175	1744	1755			174433	
3058	431929808	355	1757	1808			175746	
3057	431929809	175	1810	1821			181051	
3056	431929810	355	1824	1835			182433	
3055	431929811	175	1837	1849			183739	
3054	431929812	355	1853	1906			185331	
3053	431929813	175	1909	1922			190900	

Julian Day 298 Flight A

LIDAR Flight Log



Date	OCT 25, 2019	Aircraft	C-FFRY
Project	3186 OSI, POWDER	Pilot	MACQUARRIE
Location	SHERIDAN, WYO.	Operator	WESTERGARD
Mission Objective			

System	REIGL Q1560i
Unit	43
IMU	
GPS Rx	Trimble
Scanner 1 Drive	
Scanner 2 Drive	

Additional Notes

Time to next maintenance: 50 hr 100 hr

Aircraft Block Time			
Engine On	1538	Takeoff	1555
Engine Off	2153	Landing	2141
Total	6.3 hrs	Total	5.8 hrs

Mission Plan			
AGL Height	2000 m	Pulse Rate	500 kHz
Target Speed	160 kts	Scan Rate	109
Laser Current	100 %	FOV	60 degs

Static Alignment	Start	End	
	Pre Mission	1546	1551
	Post Mission	2146	2151

Flight Line	LIDAR File Name	Flight Direction	GPS Time		Line Aborted		Mission ID	Comments
			Start	End	Time	nmi to End		
3052	431929814	355	1925	1938			192512	
3051	431929815	175	1941	1954			194114	
3050	431929816	355	1957	2011			195700	
3049	431929817	175	2013	2027			201354	
3048	431929818	355	2029	2044			202942	
3047	431929819	175	2046	2059			204630	
figure 8		00	2059	2105				Inertial



LIDAR Flight Log

Julian Day	089	Flt	A
------------	-----	-----	---

Date	March 29, 2020	Aircraft	CFKMA
Project	3186 QSI Powder River	Pilot	N. Emson
Location	Sheridan, WY	Operator	B. Eisenbart
Mission Objective			

System	LMS-1560
Unit	64
IMU	Applanix AP60
GPS Rx	Trimble
Scanner 1 Drive	1
Scanner 2 Drive	2

Additional Notes	
------------------	--

Aircraft Block Time			
Engine On	15:39	Ramp Out	Takeoff 15:58
Engine Off	22:17	Ramp In	Landing 22:06
Total	6.6 hrs	Total	6.1 hrs

Mission Plan			
AGL Height	2300 m	Pulse Rep Rate	400 kHz
Ground Speed	160 kts	Scan Rate	89 Hz
Laser Current	100 %	FOV	60 Deg's

Static Alignment	GPS Time	
	Start	End
Pre Mission	15:42	15:47
Post Mission	22:10	22:15

Flight Line	LiDAR File Name	Flight Direction	GPS Time		Ln Aborted Time	Date Stamp	ALS Time Stamp	Comments
			Start	End				
PPP-8	-		16:29	16:34			-	Figure 8
3046	6420089-01	351°	16:38	16:51		200329	163836	
3045	02	171°	16:55	17:08			165523	
3044	03	351°	17:12	17:26			171225	
3043	04	171°	17:30	17:44			173018	
3042	05	351°	17:47	18:01			174744	
3041	06	171°	18:05	18:18			180531	
3040	07	351°	18:22	18:35			1822125	
3039	08	171°	18:39	18:53			183927	
3038	09	351°	18:57	19:11			185711	
3037	10	171°	19:15	19:29			191502	
3036	11	351°	19:33	19:47			193307	
3035	12	171°	19:50	20:05			195048	
3034	13	351°	20:08	20:22			200856	
3033	14	171°	20:25	20:40			202541	



LIDAR Flight Log

Julian Day 089	Flt A
----------------	-------

Date	March 29, 2020	Aircraft	CFKMA
Project	3186 QSI Powder River	Pilot	N. Emson
Location	Sheridan, WY	Operator	B. Eisenbart
Mission Objective			

System	LMS-1560
Unit	64
IMU	Applanix AP50
GPS Rx	Trimble
Scanner 1 Drive	1
Scanner 2 Drive	2

Additional Notes

Aircraft Block Time		
Engine On	15:39	15:58
Engine Off	22:17	22:06
Total	6.6 hrs	6.1 hrs

Mission Plan			
AGL Height	2300 m	Pulse Rep Rate	400 kHz
Ground Speed	160 kts	Scan Rate	89 Hz
Laser Current	100 %	FOV	60 Deg's

Static Alignment	GPS Time	
	Start	End
Pre Mission	15:42	15:47
Post Mission	22:10	22:15

Flight Line	LiDAR File Name	Flight Direction	GPS Time		Ln Aborted Time	Date Stamp	ALS Time Stamp	Comments
			Start	End				
3032	15	351°	20:44	20:57		200329	204406	
3031	16	171°	21:01	21:15			210118	
X-TIE	17	81°	21:19	21:25			211945	
PPP-8	-		21:25	21:30			-	Figure 8



LIDAR Flight Log

Julian Day	090	Flt	A
------------	-----	-----	---

Date	March 30, 2020	Aircraft	CFKMA
Project	3186 QSI Powder River	Pilot	N. Emson
Location	Sheridan, WY	Operator	B. Eisenbart
Mission Objective			

System	1560
Unit	64
IMU	Applanix AP60
GPS Rx	Trimble
Scanner 1 Drive	1
Scanner 2 Drive	2

Additional Notes	Powder River 2 MOA closed today Limited to the west end of block
------------------	---

Aircraft Block Time			
Engine On	14:50	Ramp Out	Takeoff 15:10
Engine Off	20:58	Ramp In	Landing 20:46
Total	6.1 hrs	Total	hrs 5.6

Mission Plan			
AGL Height	2300 m	Pulse Rep Rate	400 kHz
Ground Speed	160 kts	Scan Rate	89 Hz
Laser Current	100 %	FOV	60 Deg's

Static Alignment	GPS Time	
	Start	End
Pre Mission	15:03	15:08
Post Mission	20:51	20:56

Flight Line	LiDAR File Name	Flight Direction	GPS Time		Ln Aborted Time	Date Stamp	ALS Time Stamp	Comments
			Start	End				
PPP-8	-		15:38	15:43			-	Figure 8
3001	6420090-01	350°	15:54	10:02			155444	
3002	02	170°	16:04	16:11			160450	
3003	03	350°	16:14	16:28			161456	
3004	04	170°	16:31	10:44			163100	small patches of snow at south end
3005	05	350°	16:49	17:02			164904	small patches of snow at south end
3006	06	170°	17:06	17:20			170647	small patches of snow at south end
4003	07	170°	17:26	17:40			172631	
4002	08	350°	17:45	17:54			174528	small patches of snow
4001	09	170°	17:58	18:08			175826	small patches of snow
X-TIE	10	80°	18:11	18:13			181127	
4004	11	350°	18:20	18:33			182007	
3007	12	350°	18:39	18:52			183902	small patches of snow at south end
3008	13	170°	18:56	19:10			185617	
3009	14	350°	19:13	19:27			191341	

Julian Day	090	Flt	A
------------	-----	-----	---

LIDAR Flight Log



Date	March 30, 2020	Aircraft	CFKMA
Project	3186 QSI Powder River	Pilot	N. Emson
Location	Sheridan, WY	Operator	B. Eisenbart
Mission Objective			

System	1560
Unit	64
IMU	Applanix AP60
GPS Rx	Trimble
Scanner 1 Drive	1
Scanner 2 Drive	2

Additional Notes	Powder River 2 MOA closed today Limited to the west end of block
------------------	---

Aircraft Block Time			
Engine On	14:50	Ramp Out	Takeoff
Engine Off	20:58	Ramp In	Landing
Total	6.1 hrs	Total	5.6 hrs

Mission Plan			
AGL Height	2300 m	Pulse Rep Rate	400 kHz
Ground Speed	160 kts	Scan Rate	89 Hz
Laser Current	100 %	FOV	60 Deg's

Static Alignment		GPS Time	
Pre Mission	15:03	Start	End
Post Mission	20:51	20:51	20:56

Flight Line	LiDAR File Name	Flight Direction	GPS Time		Ln Aborted	Date Stamp	ALS Time Stamp	Comments
			Start	End				
3010	15	170°	19:30	19:44		200330	193038	
3011	16	350°	19:48	20:01			194801	
X-TIE	17	260°	20:14	20:18			201434	
PPP-8	-		20:19	20:24			-	Figure 8



LIDAR Flight Log

Julian Day	091	Flt	A
------------	-----	-----	---

Date	March 31, 2020	Aircraft	CFKMA
Project	3186 QSI Powder River	Pilot	N. Emson
Location	Sheridan, WY	Operator	B. Eisenbart
Mission Objective			

System	1560
Unit	64
IMU	Applanix AP60
GPS Rx	Trimble
Scanner 1 Drive	1
Scanner 2 Drive	2

Additional Notes	
------------------	--

Aircraft Block Time			
Engine On	14:45	Ramp Out	Takeoff
Engine Off	18:43	Ramp In	Landing
Total	4.0 hrs	Total	3.5 hrs

Mission Plan			
AGL Height	2300 m	Pulse Rep Rate	400 kHz
Ground Speed	160 kts	Scan Rate	89 Hz
Laser Current	100 %	FOV	60 Deg's

Static Alignment	GPS Time	
	Start	End
	Pre Mission	14:55
Post Mission	18:35	18:40

Flight Line	LiDAR File Name	Flight Direction	GPS Time		Ln Aborted Time	Date Stamp	ALS Time Stamp	Comments
			Start	End				
PPP-8	-		15:28	15:33			-	Figure 8
3030	6420091-01	350°	15:37	15:50		200331	153722	
3029	02	170°	15:54	16:08			155444	
3028	03	350°	16:12	16:43			161215	
3027	04	170°	16:29	16:43			162917	virga on the south end of line - re-fly
X-TIE	05	260°	16:47	16:49			164725	
X-TIE	06	80°	16:52	16:54			165211	reflew X-TIE
4068	07	171°	17:08	17:12			170808	
4067	08	351°	17:15	17:19			171527	
4066	09	171°	17:22	17:34			172250	patches of snow at south end - re-fly
X-TIE	10	261°	17:48	17:50			174841	clouds moving in from the west
PPP-8	-		17:50	17:55			-	Figure 8

Julian Day **113** Flight **A**

LIDAR Flight Log



Date 4/22/2020	Aircraft CFFRY
Project 3186_QSI_PowderRiver_QL2	Pilot J.MATHIESON
Location KSHR	Operator C.EDGAR
Mission Objective Weather:	
KAR location:	

System VQ-1560I
Unit 38
IMU Applanix
GPS Rx Trimble
Scanner 1 Drive
Scanner 2 Drive

Additional Notes
29.1 - today = hrs to 100hr
Time to next maintenance: <input type="checkbox"/> 50 hr <input type="checkbox"/> 100 hr

Aircraft Block Time	
Engine On 14:53	Takeoff 15:12
Engine Off 21:56	Landing 21:44
Total 7.1 hrs	Total 6.5 hrs

Mission Plan			
AGL Height 2000	m	Pulse Rate 500	
Target Speed 160	kts	Scan Rate 109Hz	
Laser Current 100	%	FOV 60	degs

Static Alignment	Start	End
	Pre Mission	14:56
	Post Mission	21:49
GPS Time		21:54

Flight Line	LiDAR File Name	Flight Direction	GPS Time		Line Aborted		Mission ID	Comments
			Start	End	Time	nmi to End		
TEST			1516	1516			200422 Time Stamp	
F8			1533	1538			161538	
XTIE			1538	1548			153905	
3027			1552	1606			155257	
3026			1610	1623			161002	
3025			1626	1639			162625	
3024			1643	1657			164316	
3023			1700	1714			170002	
3022			1716	1730			171635	
3021			1732	1745			173042	
3020			1748	1801			174858	
3019			1806	1819			180603	
3018			1822	1836			182249	
3017			1839	1852			183922	
3016			1856	1910			185604	

Date 4/22/2020	Aircraft CFFRY
Project 3186_QSI_PowderRiver_QL2	Pilot J.MATHIESON
Location KSHR	Operator C.EDGAR
Mission Objective: _____ Weather: _____ KAR location: _____	

System VQ-1560I
Unit 38
IMU Applanix
GPS Rx Trimble
Scanner 1 Drive
Scanner 2 Drive

Additional Notes

Time to next maintenance: _____ 50 hr 100 hr

Aircraft Block Time	
Engine On 14:53	Takeoff 15:12
Engine Off 21:56	Landing 21:44
Total 7.1 hrs	Total 6.5 hrs

Mission Plan		
AGL Height	2000 m	Pulse Rate 500
Target Speed	160 kts	Scan Rate 109Hz
Laser Current	100 %	FOV 60 degs

Static Alignment		GPS Time	
Pre Mission	Start	14:56	End
Post Mission	21:49	21:49	21:54

Flight Line	LiDAR File Name	Flight Direction	GPS Time		Line Aborted		Mission ID	Comments
			Start	End	Time	nmi to End		
3015			1912	1925			200422	
3014			1928	1943			191222	
3013			1945	1959			192834	
3012			2001	2015			194509	
3008			2017	2030			200123	
3007			2034	2047			201752	
3006			2050	2103			203409	
F8			2104	2109			205043	



Project	USGS Ravalli Granite Cluster Powder River	Aircraft Tail Number	Aircraft Make/Model	Sensor	Mission ID	Date	Project Name	Flight Plan	Lines Flown	Flight 1 Wheels Up Down	Flight 1 Begin End	Flight 1 Wheels Up End	Flight 2 Wheels Up Down	Flight 2 Begin End	Flight 2 Wheels Up End	Operator	Pilot	Base of Operations	Notes	
4/20/2020	20200420	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200420	20200420	MT Counties R035553	USGS Ravalli County Q12	26-32	10:52:00 AM	5:18:00 PM	14:42:33	6:51:00 PM	14:43:18	14:55:06	Stephane Conse	Brian Butler	KGTF	We finally got our weather window today! We acquired what we could of the Ravalli	
5/9/2020	20200509	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200509	20200509	MT Counties R035553	USGS Ravalli County Q12	26-32	10:29:00 AM	2:20:00 PM	14:49:04	10:29:00 AM	14:49:04	14:49:04	Scott Nash	Chris Gatman	KGTF	Looked like the clouds were filling in our priority area but around 10 they cleared back in. Ravalli by cloud cover. We were able to get a go. Lots of clouds around but we at least got a handful of lines in after an hour of cloud breaks.	
5/30/2020	20200530	SN4045	Cessna Caravan 208	Regi VO-1560 SN4045	20200530	20200530	MT Counties R035553	USGS MT Counties Base Q12, feeding	79-86	8:42:00 AM	12:51:00 AM	7:97	8:42:00 AM	12:51:00 AM	7:97	Scott Nash	Chris Gatman	KGTF	Flown earlier before we got clouded out.	
6/2/2020	20200602	SN4045	Cessna Caravan 208	Regi VO-1560 SN4045	20200602	20200602	MT Counties R035553	USGS MT Counties Base Q12, feeding	87-89, 110-116	9:02:00 AM	11:36:00 AM	8:00:1.1	9:02:00 AM	11:36:00 AM	8:00:1.1	Noah Edison	Chris Gatman	KBTM	Started where we left off Saturday. Clouds started pepping up in the way and it looked like there were a few. Then we switched to another block that was cloud and snow free and we were able to get a good amount of lines in with poor weather quickly approaching called it a day.	
6/2/2020	20200602	SN4045	Cessna Caravan 208	Regi VO-1560 SN4045	20200602	20200602	MT Counties R035553	USGS MT Counties Base Q12, feeding	11-20, 30-32, 36-39, 47-47, 48-49, 50	9:06:00 AM	2:54:00 PM	8:00:3.7	9:06:00 AM	2:54:00 PM	8:00:3.7	Noah Edison	Chris Gatman	KMSO	Got in full of data, collecting today! Our first target AOP still had scattered clouds when we arrived so we began work on our second target. The weather was not great with us as we flew lines progressing east before bumping into the snow coming off the mountains. The snow became too much. Flew a few lines for the mission's low handed snow clouds, encountered heavy turbulence and decided to head back to base.	
6/2/2020	20200602	SN4045	Cessna Caravan 208	Regi VO-1560 SN4045	20200602	20200602	MT Counties R035553	USGS MT Counties Base Q12, feeding	Base Q12 87-88	9:22:00 AM	11:59:00 AM	8:09:5	9:22:00 AM	11:59:00 AM	8:09:5	Noah Edison	Chris Gatman	KMSO	We flew most of the snowfree lines in the northern section of Base Q12 before returning to KMSO to prep for upcoming maintenance.	
6/2/2020	20200602	SN4045	Cessna Caravan 208	Regi VO-1560 SN4045	20200602	20200602	MT Counties R035553	USGS MT Counties Base Q12, feeding	Base Q12 4b, 5a, 80-91, 117-123	9:11:00 AM	2:08:00 PM	8:01:3	9:11:00 AM	2:08:00 PM	8:01:3	Noah Edison	Chris Gatman	KJAO	We collected on USGS MT Q12 until we ran out of snow free areas.	
6/23/2020	20200623	SN0361	Cessna Caravan 208B	Regi VO-1560 SN0361	20200623	20200623	MT Counties R035553	USGS Ravalli County Q12	11-10, 123, 124, 36-39, 47-47, 48-49, 50, 107-107	7:30:00 AM	12:36:00 PM	2:123	7:30:00 AM	12:36:00 PM	2:123	Ein Gulikov	Tyler Lundquist	KHLN	Got a good fill in targeting whatever was snowed and cloud free.	
6/29/2020	20200629	SN0361	Cessna Caravan 208	Regi VO-1560 SN0361	20200629	20200629	MT Counties R035553	USGS Montana Counties Base Q12	48-49, 50	8:53:00 AM	2:55:00 PM	2:137.6	8:53:00 AM	2:55:00 PM	2:137.6	Scott White	Nathan Sharp	KMSO		
7/2/2020	20200702	SN4040	Piper Navajo	Regi VO-1560 SN4040	20200702	20200702	MT Counties R035553	Flight 1 addms, flight 2 montana counties	addms, 21-24	9:00:00 AM	1:29:00 AM	10:73.1	9:00:00 AM	1:29:00 PM	10:73.1	Mark Sessions	Alex Sessions	KMSO		
7/2/2020	20200702	SN4040	Piper Navajo	Regi VO-1560 SN4040	20200702	20200702	MT Counties R035553	Montana counties	144, 124, 125	8:50:00 AM	10:42:00 AM	10:718.8	8:50:00 AM	10:42:00 AM	10:718.8	Mark Sessions	Alex Sessions	KMSO	none	
7/2/2020	20200702	SN4040	Piper Navajo	Regi VO-1560 SN4040	20200702	20200702	MT Counties R035553	Montana counties	13-25, 36-42	8:30:00 AM	12:29:00 PM	10:719.4	8:30:00 AM	12:29:00 PM	10:725.2	Mark Sessions	Alex Sessions	KMSO	none	
7/29/2020	20200729	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200729	20200729	MT Counties R035553	Montana counties	43-49 1-12	8:33:00 AM	1:16:00 PM	10:725.8	8:33:00 AM	1:16:00 PM	10:729.4	4.6	Mark Sessions	Alex Sessions	KMSO	completer flwable block
7/29/2020	20200729	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200729	20200729	MT Counties R035553	Adson	231-233, 284-282-531	8:36:00 AM	2:56:00 PM	7:697	8:36:00 AM	2:56:00 PM	7:697	Ben Miller	Dan Luckett	KMSO	Launched for Adson with all areas of rain to continue with snow around and acquire without incident until launched for MT counties adson.	
7/30/2020	20200730	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200730	20200730	MT Counties R035553	USGS MT Counties Base addn Q11	55-71, 323-328, 332, 365-369	8:36:00 AM	2:09:00 PM	7:693.2	8:36:00 AM	2:09:00 PM	7:693.2	Ben Miller	Dan Luckett	KMSO	Launched for MT counties adson. snowed out ATB by which we the clouds and first we had fog on it, continued where we left off and working another. No issues.	
7/31/2020	20200731	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200731	20200731	MT Counties R035553	Q11	Q11, 356-357, 40-46, 68-73	7:29:00 AM	3:07:00 PM	7:705.8	7:29:00 AM	3:07:00 PM	7:705.8	Ben Miller	Dan Luckett	kmsa	Launched for Q11, acquired within no issues.	
8/1/2020	20200801	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200801	20200801	MT Counties R035553	Q11, Q12	73	7:48:00 AM	2:55:00 PM	7:713.4	7:48:00 AM	2:55:00 PM	7:713.4	Ben Miller	Dan Luckett	kmsa	Launched for Q11, snow Q12, acquired without incident, snow on peaks.	
8/2/2020	20200802	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200802	20200802	MT Counties R035553	Q12	92-107, 125	7:34:00 AM	12:25:00 PM	2:720.3	7:34:00 AM	12:25:00 PM	2:720.3	Ben Miller	Dan Luckett	kmsa	Launched for remaining Q12 blocks. snowed out for a few minutes. block completed. Track air aborted two lines that were below, and after 10 minutes we were able to get the 5th doc and compressed folder on operator updates.	
8/2/2020	20200803	SN6546	Cessna Caravan 208B	Regi VO-1560 SN6546	20200803	20200803	MT Counties R035553	Q12	125-141	7:31:00 AM	10:57:00 AM	7:725	7:31:00 AM	10:57:00 AM	7:725	Ben Miller	Dan Luckett	kmsa	Launched for remaining snow free lines, no updates.	

8/21/2020	20200821	SN6546	Regl VO-1560	SN6546	Cecilia Caravan 208E	704MD	MT Counties R035553	USGS MT Counties QLI addn R035553	270-281	9:20:00 AM	11:28:00 AM	14790.9	14794.5	3.6	3.6	Spencer Beck	Chris Gatman	KMSO	One lift for MT Counties addn QLI. We were unable to get the addn MOVED to the project near Missoula. We flew on line for a little over two hours and the addn was not at the altitude in the mountains got really bad. We were unable to stay in the air for the entire flight. The addn was in the mountains. There was a lot of turbulence from trees, but nothing too significant.
8/22/2020	20200822	SN6546	Regl VO-1560	SN6546	Cecilia Caravan 208E	704MD	MT Counties R035553	USGS MT Counties Base QLI Addn, and Base QLI2	QLI addn: 409-421 QLI2 7478	7:28:00 AM	12:39:00 PM	14794.5	14799.7	5.2	5.2	Spencer Beck	Chris Gatman	KMSO	One lift for USGS MT Counties. We collected data on MT Counties Base QLI2 and completed this block today. The terrain was very hilly and the terrain was visible. After finishing the block we worked on the addn. We were able to get the QLI addn back. The addn was slightly better in this area. There were some small patches of snow on the ground. The addn was better data when the wind became stronger and it was hard to maintain the proper groundspeed.
8/23/2020	20200823	SN6546	Regl VO-1560	SN6546	Cecilia Caravan 208E	704MD	MT Counties R035553	USGS MT Counties Base QLI Addn 893pm	249-269 236-247-402- 408	7:52:00 AM	12:15:00 PM	14796.7	14804.4	4.7	4.7	Spencer Beck	Chris Gatman	KMSO	One lift for MT Counties Base QLI Addn. We flew just over half of a lift and the addn was not returned to base. There was smoke turbulence became too bad and we returned to base. Smoke seemed to be getting worse later in the day.
8/26/2020	20200826	SN6046	Regl VO-1560	SN6046	Cecilia Caravan 208E	604MD	MT Counties R035553	USGS MT Counties Base addn QLI		9:29:00 AM	1:39:00 PM	4951.5	4955.6	4.1	4.1	Scott White	Jamson Neilson	KMSO	Got lucky and dodged heavy fog and returned to base. We flew up the MT Counties base project.

Project	USGS Reall Granite Custer P-elder River	Aircraft Mission/Model	Aircraft Tail Number	Project Name	Flight Plan	Lines Flown	Flight 1 Week: Up (PPT)	Flight 1 Week: Down (PPT)	Flight 1 Begin Hobbs	Flight 1 End Hobbs	Flight 1 Wheel Up	Flight 2 Down	Flight 2 Begin Hobbs	Flight 2 End Hobbs	Flight 2 Daily Hobbs	Operator	Pilot	Base of Operations (Airport, FOO)	Notes	
8/26/2020	2000078 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	USGS Mountain Course Base Q1	18-20	9:05:00 AM	4:30:00 PM	2116	2145	2:9		0.0	2.9	2.9	Erin Galbraith	Tyler Ludenour	KS4N	Went up to scout out LOC, correct position. Show elevation and small patterns in the area. We were prevented from flying due to low fuel. We were able to collect a few lines but scattered patterns at the south end.	
7/26/2020	2000078 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	Adrian Nave and Adam Q1, then MT Courses Base	108-136-128 47-135A	10:15:00 AM	4:55:00 PM	7873	7973	6.5		0.0	6.5	6.5	Ben Miller	Dan Ludest	KS50	Landed for MT Courses adon. We explored various holes other than heavy sub and a few 2.7.2.2.	
7/26/2020	2000078 SN356A & B	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses Base adon	460-477		8:45:00 AM	3:07:00 PM	7893.1	7893.1	6.3		0.0	6.3	6.3	Ben Miller	Dan Ludest	KS50	Landed for southern adon line. Acquired several error associated locations and photos taken.	
7/27/2020	2000077 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses R035653	175-191		8:00:00 AM	8:49:00 AM	10731.5	10731.5	1.1	1:32:00 PM	10731.5	10731.5	4.0	Christopher Stronach	Matthew Achtmann	KS50	Good flight, no issues to report.	
7/27/2020	2000077 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	432-469		9:05:00 AM	4:09:00 PM	7891	7897	8.9		0.0	8.9	8.9	Ben Miller	Dan Ludest	KS50	Landed for MT Courses adon line.	
7/28/2020	2000078 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses R035653	192-206		9:06:00 AM	12:29:00 AM	10734.4	10734.5	3.1		0.0	3.1	3.1	Christopher Stronach	Matthew Achtmann	KS2N	Flare line near KS2N. Check show flight plan above and below path outside the Q1, no result for additional data used for good.	
7/29/2020	2000078 SN356A & B	Repl VQ-1503 SN356	Piper Navajo	MT Courses Base Q1 revamp	208-224		8:18:00 AM	11:30:00 AM	10740.3	10740.3	2.8	2:01:00 PM	10740.3	10740.3	4.5	Christopher Stronach	Matthew Achtmann	KS2N	The performance in AD our second mission about.	
8/4/2020	2000080 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	1-46-165-77		7:49:00 AM	2:41:00 PM	7735.2	7735.2	6.9		0.0	6.9	6.9	Ben Miller	Dan Ludest	KS2N	Landed from KS50 and landed on Q1. No map. No issues. Theory AD.	
8/5/2020	2000080 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	41-66-78-104		7:41:00 AM	2:36:00 PM	7735.2	7741.9	6.6		0.0	6.6	6.6	Ben Miller	Dan Ludest	KS2N	Continued on Q1. More lines for 7014MS.	
8/7/2020	2000080 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	398-310		8:45:00 AM	12:26:00 PM	14741.1	14744.1	3.3		0.0	3.3	3.3	Maranda Geller	Chris Larosa	KS2N	Good flight for 4th day of job.	
8/8/2020	2000080 SN356A & B	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	244-297		7:58:00 AM	12:18:00 PM	14744.1	14748.8	4.7	1:50:00 PM	14748.8	14751.7	2.9	7.6	Maranda Geller	Chris Larosa	KS2N	Good flight, got out early to avoid sub 2 mission.
8/9/2020	2000080 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	136-174		7:33:00 AM	12:30:00 PM	14761.7	14756.6	4.9		0.0	4.9	4.9	Maranda Geller	Chris Larosa	KS2N	Flare line back with 202E only 3 lines remain in entire area.	
8/9/2020	2000080 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses Base Q1 revamp	121-132		7:56:00 AM	3:48:00 PM	10780.6	10782.8	2.2	1:08:00 PM	10782.8	10783.5	0.7	2.9	Christopher Stronach	Matthew Achtmann	KS2N	Flare line on MT Courses, no results with three lines left. More results to go. No results for the area. One line just inside the area. One line not on sub.
8/10/2020	2000080 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses Base Q1 revamp	133-151		10:05:00 AM	11:03:00 AM	10783.5	10784.5	1.0		0.0	1.0	1.0	Christopher Stronach	Matthew Achtmann	KS2N	Flare line three lines of back.	
8/17/2020	2000081 SN356A & B	Repl VQ-1503 SN356	Piper Navajo	MT Courses R035653	192-210		8:05:00 AM	11:41:00 AM	10780.5	10783.1	2.6	1:25:11 PM	10783.1	10784.2	1.1	3.7	Alex Pustanack	Alex Sessions	KS2M	more to KS2M, will correct project.
8/18/2020	2000081 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses R035653	104-117-211-218		8:21:00 AM	11:38:00 AM	10784.2	10787.5	3.3		0.0	3.3	3.3	Alex Pustanack	Alex Sessions	KS2N	continued on why, afternoon during leg of trip to KS20081.	
8/20/2020	2000080 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	USGS MT Courses Base Q1 Adon	248-289		7:55:00 AM	12:15:00 PM	14783.7	14804.4	4.7		0.0	4.7	4.7	Spencer Back	Chris Giffman	KS50	One of MT Courses Base Q1 Adon. We explored various holes other than heavy sub and a few 2.7.2.2. We were able to collect a few lines but scattered patterns at the south end.	
8/20/2020	2000080 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses R035653	219-226		8:45:00 AM	11:07:00 AM	10784.2	10788.8	1.4		0.0	1.4	1.4	Alex Pustanack	Greg Smonds	KS2N	Flare line a little more today, visibility continues to be challenge.	
8/20/2020	2000080 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses R035653	227-243		8:40:00 AM	10:07:00 PM	10780.8	10782.2	2.4		0.0	2.4	2.4	Jonathan Shaw	Greg Smonds	KS2N	Flare line on why, afternoon during leg of trip to KS20081.	
8/20/2020	2000080 SN356A	Repl VQ-1503 SN356	Cessna Caravan 208B	MT Courses R035653	1-11		8:31:00 AM	2:55:00 PM	4963.7	4963.7	5.1		0.0	5.1	5.1	Scott White	Jamon Nelson	KS50	Flare line on why, afternoon during leg of trip to KS20081.	
8/20/2020	2000080 SN356A	Repl VQ-1503 SN356	Piper Navajo	MT Courses R035653	118-121 and 1-20 on the refueling		8:30:00 AM	12:18:00 PM	10782.2	10785.9	3.7		0.0	3.7	3.7	Jonathan Shaw	Greg Smonds	KS2N	One of today to finish the 2555 Q1. Lines in addition to the why, 1871 line and 1871.	